



SINGLE CHANNEL WIRELESS LENS CONTROL WLC-TO4

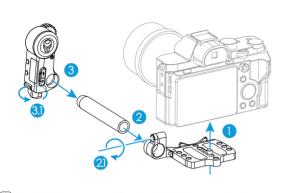
• Nucleus-Nano Motor x1

CHECKING LIST:

- Nucleus-Nano Handwheel Controller x1
- 15mm Single Rod Mounting Baseplate x1
- 15mm x 100mm Aluminum Black Rod x1 • Photo Lens Follow Focus Gear Ring x 2
- Handwheel Attachment Plate for G2X and Ronin-S x1 • Handwheel Attachment Adapter for Zhiyun Crane x1
- Micro USB to Micro USB Nano Motor Power Cable x1
- 14500 Battery Charger x1
- 14500 Batteries x2
- M4 Allen Key x1
- M6 Allen Key x1 • 1/4 Allen Kev x1
- User Guide x1
- · Cardboard Box x1

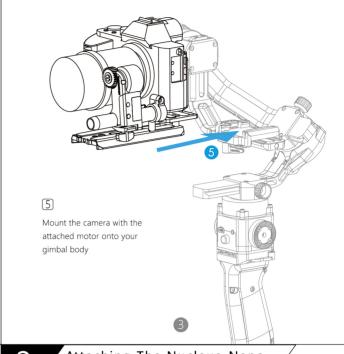


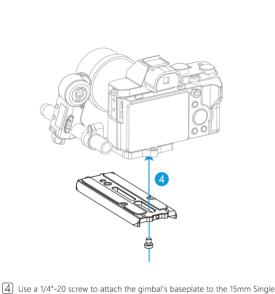
Attaching The Motor



- 1 Use 1/4"-20 screw to mount the baseplate to the camera body
- [2] Insert the rod into the 15mm Single Rod Mounting Baseplate
- 3 Loosen the motor's hand-tightened screw and attach the motor to the rod. Rotate the motor so that it rests against the lens' focus gear, then tighten the screw

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Rod Mounting Baseplate

Attaching The Nucleus-Nano Handwheel Attachment Plate *Example Shown with Tilta Gravity G2X

TILTA GRAVITY G2X and DJI RONIN-S

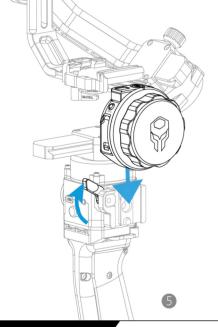
Use the included M6 screw to attach the plate to the handle of the Gravity G2X and the Ronin-S's M4 screw to attach it to the handle of the Ronin-S

ZHIYUN CRANE

Loosen the hand-tightened screw of the Handwheel Attachment Plate Adapter for Zhiyun Crane, then clamp it around the handle of the gimbal. Tighten the hand-tightened screw to secure the adapter. Then use the included M6 screw to attach the Handwheel Attachment Plate



Attaching The Handwheel



Make sure the red toggle is flipped to the upmost position. Next, slide the handwheel into the plate and lower the red toggle to lock it into place

2. Auto-calibrate the motor to the range of the lens For lenses with hard stops at close focus and infinity. Hold 【Cal】 button

for 3 seconds to engage the motor's auto-calibration

Click and hold [Cal] for 3 secs to automatic calibration. For lenses with no hard stops at close focus and infinity Turn the handwheel to where your lens reads close focus and double press [Cal] to set the close focus end of the handwheel . Turn the handwheel to where your lens reads infinity and double press [Cal] to set the infinity end of the handwheel The manual calibration is now complete

3. Setting an A-B range to the handwheel

Rotate the handwheel to the desired position of the A mark and press 【SET】 to create an A mark. Then rotate the handwheel to the desired position of the B mark and press [SET] to create a B mark The LCD display will show the marks that you have set. Simply press

[SET] again to delete your A-B range



5. Calibrate Handwheel

Link your camera's compatible R/S cable (optional) from your camera's R/S port into the Nucleus-Nano Motor's LANC port. Then click 【REC】 to start/stop the record function on your camera



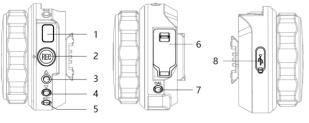
When turning the handwheel to the close focus or infinity end of its range, the motor quickly spins back to the other side of it's calibrate range

Hold the Δ button to enter the handwheel's menu then cycle through the menu to find <code>[Cal Knob]</code> . Press the ∇ button to find <code>[Cal Knob]</code> then double click the Δ button to confirm and follow the on screen instructions

5.1 When do you need to calibrate the handwheel?

5.2 How to calibrate the handwheel?

FUNCTION Nucleus-Nano Handwheel



- 1. Menu Display Screen
- 2. Power and R/S control 3. UP button
- 4. DOWN button
- 5. SET button 6. Battery Compartment

8. Micro-USB port

7. Calibration button

POWER ON/OFF Press [REC] to power unit on



Hold [REC]

The unit will turn off in 3 sec

in 3s

6. Assigning the Wireless Control







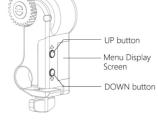
MASTER: The Nucleus-Nano Handwheel Controller is in control of the **SLAVE**: Releases the control from the Nucleus-Nano Handwheel controller

to either the Nucleus-M's FIZ hand unit or Nulcleus-M hand grips



FUNCTION Nucleus-Nano Motor





1. Set the Channel





Use the $\Delta \nabla$ buttons to adjust the channel numbers of both the handwheel and motor to the same channel so that they can communicate with each other





